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Editor-in-Chief

Haluk Berk

Dokuz Eylül University, School of
Medicine, İzmir Turkey
editor@aott.org.tr

Former Editor-in-Chief

Önder Kılıçoğlu

İstanbul University, İstanbul School of
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International Scientific Review Consultants

Enrique Gomez-Barrena

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Publisher
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Contact Address:
Büyükdere Cad. 105/9 34394
Mecidiyeköy, Şişli, İstanbul, Turkey
Phone: +90 212 217 17 00
Fax: +90 212 217 22 92
E-mail: info@avesyayincilik.com



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The aim of the journal is to publish original studies of the highest scientific and clinical value in orthopedics, traumatology, and related disciplines. The scope of the journal includes but not limited to diagnostic, treatment, and prevention methods related to orthopedics and traumatology. Acta Orthopaedica et Traumatologica Turcica publishes clinical and basic research articles, case reports, personal clinical and technical notes, systematic reviews and meta-analyses and letters to the Editor. Proceedings of scientific meetings are also considered for publication.

The target audience of the journal includes healthcare professionals, physicians, and researchers who are interested or working in orthopedics and traumatology field, and related disciplines.

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Editor-in-Chief: Prof. Dr. Haluk Berk

Address: TOTDER Genel Merkezi, Şehremini, Koyuncu Sk. No: 4/5 , 34104 Fatih, İstanbul, Turkey

Phone: +90 212 530 15 08

Fax: +90 212 530 15 21

E-mail: editor@aott.org.tr

Publisher: AVES

Address: Büyükdere Cad., 105/9 34394 Mecidiyeköy, Şişli, İstanbul, Turkey

Phone: +90 212 217 17 00

Fax: +90 212 217 22 92

E-mail: info@avesyayincilik.com

Web page: www.avesyayincilik.com



AOTT

ACTA ORTHOPAEDICA et TRAUMATOLOGICA TURCICA

CONTENTS

From the Editor

Research Articles

- 285** Is it advantageous to use the intraoperative compression option of proximal femoral nail antirotation in the treatment of osteoporotic intertrochanteric fractures? A retrospective comparative study
Hong Man Cho, Ji Yeon Park, Ki Hyun Kwon, Young Lee
- 293** Comparison of systemic inflammatory responses of proximal femoral nail versus dynamic hip screw after treatment of patients with pertrochanteric fractures: A Prospective comparative study
Kushtrim Grezda, Mislav Jelic, Armond Daci, Cen Bytyqi, Qerim Kida
- 299** A new modification of the Trapdoor Procedure without surgical hip dislocation in the management of patients with osteonecrosis of the femoral head: A retrospective case series
Budak Akman, Melih Güven, Barış Kadioğlu, Namık Kemal Özkan, Ömer Yonga, Burak Özturan
- 306** The effect of a preoperative physical therapy education program on short-term outcomes of patients undergoing elective total hip arthroplasty: A controlled prospective clinical trial
Marina Pinskiy, Omri Lubovsky, Leonid Kalichman
- 311** Results of the Novation Crowncup™ porous-coated uncemented acetabular component in total hip arthroplasty: a 10-year clinical and radiological assessment
Daniel Godoy-Monzon, Agustin Garcia-Mansilla, Alberto Cid Casteulani, Santiago Svarzchtein
- 316** Effect of adding dexmedetomidine to intra-articular levobupivacaine on postoperative pain following arthroscopic meniscus surgery: A prospective, double-blind, randomized, placebo- controlled, clinical trial
Onur Avci, İclal Özdemir Kol, Oğuz Gündoğdu, Zekeriya Öztumur, İdris Erşan
- 321** Ultrasonographic measurement of the dimensions of proximal and distal patellar fragments after Niebauer-King Procedure for the management of congenital dislocation of the knee
Ömer Sunkar Biçer, Mustafa Tekin, Ömer Faruk Eren, Akif Mirioğlu, Mehmet Ali Deveci, Süreyya Soyupak
- 327** Is denervation surgery possible in the treatment of hallux rigidus? An anatomic study of cadaveric specimens
Bilgehan Çatal, Mert Keskinbora, Elif Nedret Keskinöz, Gamze Tümentemur, İbrahim Azboy, Bahtiyar Demiralp
- 332** Long-term clinical outcomes of innervated digital artery perforator flap in the treatment of fingertip injuries
Ali Cavit, Osman Civan, Haluk Özcanlı



AOTT

ACTA ORTHOPAEDICA et TRAUMATOLOGICA TURCICA

- 338 Relationship between incidence of postoperative radial nerve palsy and surgical experience in the treatment of humeral shaft fractures through a posterior triceps splitting approach: A retrospective study**
Woo-Yong Lee, Hyun-Dae Shin, Kyung-Cheon Kim, Soo-Min Cha, Yoo-Sun Jeon
- 344 Five-year mortality rate for patients with diabetic hand gangrene who undergo upper extremity amputation**
Shin Woo Choi, Young Ho Shin, Jae Kwang Kim
- 349 Effect of Different Forearm Positions on fragment rotation in extra-articular distal radius fractures: A cadaveric study**
Maximilian Lenz, Maik Neumann, Christian K. Spies, Gregor Stein, Peer Eysel, Jens Dargel, Johannes Oppermann

Technical Note

- 355 Sliding rotational osteotomy for cases of dorsally angulated distal Radius malunion: A technical note**
Zaid Al-Ani, Khalid Sharif, Amitabh J Dwyer

Case Report

- 362 How to extract a broken cephalomedullary nail safely? A case presentation and review of the literature**
Adel Ebrahimpour, Farsad Biglari, Mehrdad Sadighi, Rodrigo Pesántez

Letters to the Editor

- 367 Comment on "Spinopelvic alignment does not change after bilateral total hip arthroplasty in patients with bilateral Crowe type-IV developmental dysplasia of the hip" by Can et al.**
Alpaslan Öztürk, Nazan Çevik, Yavuz Akalın
- 370 The second victim in orthopedics and traumatology**
Anna Carreras-Castañer, Carles Martin-Fumadó, César Vargas-Blasco, Josep Arimany-Manso



AOTT

ACTA ORTHOPAEDICA et TRAUMATOLOGICA TURCICA

FROM THE EDITOR

Dear AOTT readers,

COP26 climate conference will be held in Glasgow in November 2021 and has been described as “the critical moment for the world to come together to avoid global temperatures rising 1.5C above pre-industrial levels with catastrophic effects on health”.

The European Association of Science Editors (EASE) has send out invitation to scientific journal editors to join the initiative led by *UK Health Alliance on Climate Change*.¹

The aim of this call is to gather as many as journal editors together to publish the same editorial at the same time. Leading 18 journals are from every continent and several disciplines that include BMJ, The Lancet, PLOS Medicine, Dutch Journal of Medicine, Chinese Science Bulletin, Danish Medical Journal and others.

Orthopedics and Traumatology might seem to be “out of scope” in environmental issues yet, in my humble view, as healthcare providers and scholarly active individuals we are already deeply involved.

Coming back to orthopedics and traumatology, I am sure you will enjoy reading the articles we have selected for you in this issue of AOTT.

Best regards,

Haluk Berk M.D.
Editor-in-Chief
Acta Orthopaedica et Traumatologica Turcica

Reference

1. Available from: <http://www.ukhealthalliance.org>